

Springer

1st  
edition

1990, IX, 144 p. 1 illus.

**Printed book**

Softcover

**Printed book**

Softcover

ISBN 978-3-540-52947-7

\$ 119,99

Available

**Discount group**

Professional Books (2)

**Product category**

Monograph

**Series**

Lecture Notes in Control and Information Sciences

Engineering : Control , Robotics, Mechatronics

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# Minimum Entropy $H_\infty$ Control

This monograph is concerned with the design of feedback controllers for linear multivariable systems, which are robust to system uncertainty. System uncertainty can be realistically represented by including perturbations with bounded  $H_2$ -norm, and this is the approach taken here. For a given  $H_2$ -norm bound, there is a family of robustly stabilizing controllers, and the central question in this book is which of these controllers to choose. One choice to take is that which minimizes the entropy of the resulting closed loop transfer function, and the derivation and properties of this solution occupies most of this monograph. Explicit formulae are obtained for the minimum entropy solution, which is a precisely defined compromise between the Linear Quadratic Gaussian optimal solution and the  $H_2$ -optimal solution. The book will be appropriate for graduate classes requiring only a first course in state-space methods, and some elementary knowledge of  $H_2$  control and Linear Quadratic Gaussian control.

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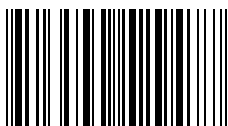
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ISBN 978-3-540-52947-7 / BIC: TJFM / SPRINGER NATURE: SCT19000

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