



2009, XX, 188 p. 73 illus.

 Printed book**Hardcover**

- ▶ 139,99 € | £119.99 | \$169.99
- ▶ *149,79 € (D) | 153,99 € (A) | CHF 154.00

 eBook

Available from your library or

- ▶ springer.com/shop

 MyCopy

Printed eBook for just

- ▶ € | \$ 24.99
- ▶ springer.com/mycopy

D. Song

Sharing a Vision

Systems and Algorithms for Collaboratively-Teleoperated Robotic Cameras

Series: Springer Tracts in Advanced Robotics, Vol. 51

- ▶ **Excellent picture of the state-of-the-art in collaboratively teleoperated robotic cameras**

The monograph written by Dezheng Song is focused on a robotic camera simultaneously controlled by multiple online users via the Internet. A challenging match between the collaboratively tele-operated robotic cameras and the needs from nature environment observation is sought, which greatly extends the domain of online robots in both application and technology development directions, including building construction site monitoring, public space surveillance, and distance education. New solutions are proposed which demonstrate the enormous potential of Internet-based infrastructures for immediate success in the market.



Order online at springer.com ▶ or for the Americas call (toll free) 1-800-SPRINGER ▶ or email us at: customerservice@springer.com. ▶ For outside the Americas call +49 (0) 6221-345-4301 ▶ or email us at: customerservice@springer.com.

The first € price and the £ and \$ price are net prices, subject to local VAT. Prices indicated with * include VAT for books; the €(D) includes 7% for Germany, the €(A) includes 10% for Austria. Prices indicated with ** include VAT for electronic products; 19% for Germany, 20% for Austria. All prices exclusive of carriage charges. Prices and other details are subject to change without notice. All errors and omissions excepted.