
Birkhäuser

 1st
edition

 1st ed. 2017, XVII, 297 p.
12 illus., 11 illus. in color.

Printed book

Hardcover

Printed book

Hardcover

ISBN 978-3-319-42377-7

 £ 99,99 | CHF 130,00 | 109,99 € |
120,99 € (A) | 117,69 € (D)

Available

Discount group

Science (SC)

Product category

Monograph

Series

 Systems & Control: Foundations &
Applications

Other renditions

Softcover

ISBN 978-3-319-82564-9

Softcover

ISBN 978-3-319-42379-1

Mathematics : Systems Theory, Control

Karafyllis, Iasson, Krstic, Miroslav

Predictor Feedback for Delay Systems: Implementations and Approximations

- **First book to study the implementation issues of predictor feedback and provide formulas for the uncertainty gains of time-delay systems with large input and/or measurement delays**
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This monograph bridges the gap between the nonlinear predictor as a concept and as a practical tool, presenting a complete theory of the application of predictor feedback to time-invariant, uncertain systems with constant input delays and/or measurement delays. It supplies several methods for generating the necessary real-time solutions to the systems' nonlinear differential equations, which the authors refer to as approximate predictors. Predictor feedback for linear time-invariant (LTI) systems is presented in Part I to provide a solid foundation on the necessary concepts, as LTI systems pose fewer technical difficulties than nonlinear systems. Part II extends all of the concepts to nonlinear time-invariant systems. Finally, Part III explores extensions of predictor feedback to systems described by integral delay equations and to discrete-time systems. The book's core is the design of control and observer algorithms with which global stabilization, guaranteed in the previous literature with idealized (but non-implementable) predictors, is preserved with approximate predictors developed in the book.

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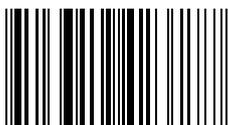
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ISBN 978-3-319-42377-7 / BIC: GPFC / SPRINGER NATURE: SCM13070

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