

# Contents

<b>1</b>	<b>Introduction</b> .....	1
<b>2</b>	<b>MISO Takagi-Sugeno Fuzzy System with Linear Membership Functions</b> .....	3
2.1	Perfect Approximation of Nonlinear Functions Using the Simplest Takagi-Sugeno Model .....	3
2.2	Assumptions and Linguistic Interpretation of Linear Membership Functions .....	7
2.3	Compact Description of the MISO TS System .....	9
2.4	Crisp Output of the Zero-Order MISO P1-TS System .....	11
2.5	Completeness and Noncontradiction in Rule-Based Systems Defined by Metarules .....	16
2.6	Matrix Description of the MIMO Fuzzy Rule-Based System .....	18
2.7	Equivalence Problem in the Rule-Based Systems .....	20
2.8	Summary .....	23
<b>3</b>	<b>Recursion in TS Systems with Two Fuzzy Sets for Every Input</b> .....	25
3.1	Some Features of the Fundamental Matrix and Its Inverse .....	25
3.2	Theorem on Recursion for P1-TS Systems .....	27
3.2.1	Rule-Base Decomposition .....	28
3.2.2	Crisp Output Calculation for P1-TS System Using Recursion .....	29
3.3	Recursion in More General TS Systems with Two Fuzzy Sets for Every Input .....	31
3.4	MIMO TS Systems with Inference Concerning the Structure Parameters .....	38
3.5	Boundedness of P1-TS Systems .....	57
3.6	Summary .....	58

<b>4</b>	<b>Fuzzy Rule-Based Systems with Polynomial Membership Functions</b>	61
4.1	TS Systems with Two Polynomial Membership Functions for Every Input	62
4.2	The Normalized Membership Functions for P2-TS Systems	64
4.3	SISO P2-TS System	66
4.4	P2-TS System with Two and More Inputs	69
4.4.1	Rule-Base Structure for Two-Inputs-One-Output P2-TS System	71
4.4.2	Rule-Base Structure for Three-Inputs-One-Output P2-TS System	72
4.5	The Fundamental Matrix for MISO P2-TS System	73
4.6	Recursion in MISO P2-TS Systems	83
4.6.1	Rule-Base Decomposition	84
4.6.2	Crisp Output Calculation for P2-TS System Using Recursion	86
4.7	Recursion in More General TS Systems with Three Fuzzy Sets for Every Input	96
4.8	Summary	99
<b>5</b>	<b>Comprehensive Study and Applications of P1-TS Systems</b>	101
5.1	P1-TS Systems with Two Inputs	102
5.1.1	General Case	102
5.1.2	A Simple Controller Design for a Milk of Lime Blending Tank	103
5.1.3	P1-TS Systems with Inputs and Outputs from the Unity Interval	107
5.2	P1-TS Fuzzy Systems with Three Inputs	110
5.2.1	General Case	110
5.2.2	Examples of Highly Interpretable P1-TS Systems with Three Inputs	111
5.3	Examples of P1-TS Systems with Four and More Inputs	121
5.3.1	Low Order Atmospheric Circulation Model	129
5.3.2	Induction Motor Model	132
5.3.3	Acclimatization Chamber Model	137
5.4	Optimal Fuzzy Control System Design for Second Order Plant	139
5.4.1	Highly Interpretable Fuzzy Rules for PID Controller	139
5.4.2	Optimal PID Fuzzy Controller for Linear Second Order Plant	141
5.4.3	PD-Like Optimal Controller for Nonlinear Second Order Plant	143

5.5	P1-TS System as Controller with Variable Gains .....	148
5.6	Exact Modeling of Single-Input Dynamical Systems .....	151
5.7	Exact Modeling of MIMO Linear Dynamical Systems .....	160
5.8	Strong Triangular Fuzzy Partition .....	164
5.9	Linearity Condition for P1-TS Systems .....	174
5.10	The First-Order P1-TS Systems .....	175
5.11	Zero-Order TS System with Contradictory Rule-Base .....	177
5.12	Summary .....	179
<b>6</b>	<b>Modeling of Multilinear Dynamical Systems from Experimental Data .....</b>	<b>183</b>
6.1	Problem Statement .....	183
6.2	Problem Solution .....	184
6.3	Analytical Solution for Dynamical Systems with Two Variables .....	188
6.4	Estimation of P1-TS Model by Recursive Least Squares ....	195
6.5	Summary .....	196
<b>7</b>	<b>Binary Classification Using P1-TS Rule Scheme .....</b>	<b>199</b>
7.1	Problem Description .....	200
7.2	The Fuzzy Rules with Proximity Degrees .....	202
7.3	Binary Classifier Equation .....	203
7.4	P1-TS System with Similarity Degrees as Optimal Binary Classifier .....	210
7.5	The Regularization Algorithm and Support Vector Machines .....	213
7.6	Summary .....	215
<b>A</b>	<b>Kronecker Product of Matrices .....</b>	<b>217</b>
<b>B</b>	<b>Generators and Fundamental Matrices for P1-TS Systems .....</b>	<b>219</b>
B.1	Formulas for $n = 1$ .....	219
B.1.1	Vertices of the Interval $D^1 = [-\alpha_1, \beta_1]$ .....	219
B.1.2	Generator .....	219
B.1.3	Fundamental Matrix and Its Inverse .....	219
B.2	Formulas for $n = 2$ .....	220
B.2.1	Vertices of the Rectangle $D^2 = [-\alpha_1, \beta_1] \times$ $[-\alpha_2, \beta_2], \dots$ .....	220
B.2.2	Generator .....	220
B.2.3	Fundamental Matrix and Its Inverse .....	220
B.3	Formulas for $n = 3$ .....	221
B.3.1	Vertices of the Cuboid $D^3 =$ $[-\alpha_1, \beta_1] \times [-\alpha_2, \beta_2] \times [-\alpha_3, \beta_3] \dots$ .....	221
B.3.2	Generator .....	221
B.3.3	Fundamental Matrix and Its Inverse .....	221

B.4	Formulas for $n = 4$ .....	222
B.4.1	Vertices of the Hypercuboid	
	$D^4 = [-\alpha_1, \beta_1] \times \dots \times [-\alpha_4, \beta_4]$ .....	222
B.4.2	Generator .....	223
B.4.3	Fundamental Matrix and Its Inverse .....	223
<b>C</b>	<b>Proofs of Theorems, Remarks and Algorithms</b> .....	231
C.1	Proof of Remark 3.2 .....	231
C.2	Proof of Remark 3.3 .....	232
C.3	Proof of Corollary 5.27 .....	233
C.4	Proof of RLS Algorithm from Section 6.4 .....	234
	<b>References</b> .....	237
	<b>Index</b> .....	249



<http://www.springer.com/978-3-540-89926-6>

Analytical Methods in Fuzzy Modeling and Control

Kluska, J.

2009, XXVI, 251 p. 56 illus., Hardcover

ISBN: 978-3-540-89926-6