

Contents

Foreword	xiii
Preface	xv
List of Figures	xix
List of Tables	xxix
Glossary of Abbreviations and Acronyms	xxxix
Co-authors to the second edition	xxxv
1 The Development of Underwater Acoustics	1
1.1 Rationale	1
1.1.1 Exploring the underwater environment	1
1.1.2 Influence of the propagation medium	2
1.1.3 Structure of sonar systems	4
1.2 Historical Highlights	5
1.2.1 The pioneers	5
1.2.2 The Second World War	6
1.2.3 After 1945	6
1.2.4 Civilian developments	7
1.3 Outline of Underwater Acoustic Applications	8
1.3.1 Military applications	8
1.3.2 Civilian applications	9
2 Underwater Acoustic Wave Propagation	13
2.1 Acoustic waves	14
2.1.1 Acoustic pressure	14
2.1.2 Velocity and density	15
2.1.3 Frequency and wavelength	16

2.1.4	The wave equation and its elementary solutions	17
2.1.5	Intensity and power	19
2.2	Logarithmic notation: Decibels and references	20
2.2.1	The decibel	20
2.2.2	Absolute references and levels	21
2.3	Basics of propagation losses	22
2.3.1	Geometric spreading losses	22
2.3.2	Absorption losses	23
2.3.3	Conventional propagation loss	27
2.3.4	Effect from air bubbles	28
2.4	Multiple paths	30
2.4.1	Notion of multiple paths	30
2.4.2	Sea-surface interference	31
2.4.3	An ideal model of multipath propagation	33
2.4.4	Average energy flux in a waveguide	35
2.4.5	General-case sound field prediction	37
2.5	Other deformations of underwater acoustic signals	38
2.5.1	Doppler effect	38
2.5.2	Time characteristics of echoes	40
2.6	Sound velocity in the ocean	41
2.6.1	Velocity parameters	41
2.6.2	Sound velocity models	42
2.6.3	Sound velocity measurements	44
2.6.4	Depth-velocity profiles	45
2.7	Geometrical investigation of the acoustic field	47
2.7.1	Depth-velocity profile refraction	47
2.7.2	Sound ray calculations in a stratified ocean	50
2.7.3	Losses from geometric spreading	52
2.7.4	Application of geometric acoustics	53
2.8	Underwater acoustic propagation: Case studies	54
2.8.1	Constant-velocity profile	54
2.8.2	Isothermal profile	56
2.8.3	Deep sound channel	58
2.9	Wave calculations of the acoustic field	62
2.9.1	Modal method	63
2.9.2	Complete solution of the wave equation in stratified media	67
2.9.3	Parabolic equation method	69
3	Reflection, Backscattering and Target Strength	75
3.1	Wave reflection on a plane interface	76
3.1.1	Interface between two fluid homogeneous media	76
3.1.2	Reflection on a layered medium	82
3.2	Backscattering from a target	85
3.2.1	Echo from a target	85
3.2.2	Target strength	86

3.3	Point targets	88
3.3.1	The ideal sphere	88
3.3.2	Fluid spheres	90
3.3.3	Scattering by gas bubbles.	91
3.3.4	Target strength of fish	92
3.3.5	Arbitrarily shaped target	94
3.3.6	Submarine echoes	94
3.4	Extended targets	96
3.4.1	Computation principle	96
3.4.2	Volume backscattering.	98
3.4.3	Surface backscattering	101
3.5	Reflection and scattering by a rough surface	103
3.5.1	Roughness and scattering.	103
3.5.2	Coherent reflection	105
3.5.3	Backscattered field	107
3.6	Reflection and scattering at ocean boundaries	112
3.6.1	Reflection and scattering at the sea surface	112
3.6.2	The seafloor	114
4	Noise and Signal Fluctuations	123
4.1	Narrow-band and wide-band noise	124
4.2	Underwater acoustic noise	128
4.2.1	Ambient noise.	128
4.2.2	Ship-radiated noise	137
4.2.3	Self-noise	143
4.2.4	Interference and acoustic compatibility	145
4.3	Two approaches to noise modeling	146
4.3.1	Noise coherence	146
4.3.2	Spatial model of noise average intensity	149
4.4	Reverberation	151
4.4.1	The concept of reverberation	151
4.4.2	Reverberation modeling.	152
4.4.3	Consequences of reverberation	153
4.5	Underwater acoustic noise reduction.	154
4.6	Environment variability and signal fluctuations	156
4.6.1	Variations in the propagation medium	156
4.6.2	Nature of signal fluctuations	158
4.6.3	Amplitude distributions associated to signal fluctuations	159
5	Transducers and Array Processing	167
5.1	Underwater electro-acoustic transducers	168
5.1.1	Fundamental principles	168
5.1.2	Underwater acoustic sources	171
5.1.3	Hydrophones	177

5.1.4	Transducer modeling and design	178
5.1.5	Transducer installation	179
5.2	Transducer characteristics	183
5.2.1	Frequency bandwidth	183
5.2.2	Electrical impedance	184
5.2.3	Sensitivity in transmission and reception	185
5.2.4	Efficiency	186
5.2.5	Underwater acoustic transducer measurements	187
5.3	The sonar transmitter	188
5.3.1	Transmission line description	188
5.3.2	Sonar amplifier technology	189
5.3.3	Impedance-matching unit	191
5.3.4	Transmission line overall structure	191
5.3.5	Source level	192
5.3.6	Maximum transmission level – Cavitation	193
5.4	Transducer and array directivity	194
5.4.1	Notion of directivity	194
5.4.2	Near field and far field	198
5.4.3	Theoretical results for simple-geometry antennas	200
5.4.4	Combining directivity patterns	203
5.4.5	Directivity of wide-band signals	204
5.4.6	Beamforming	207
5.4.7	Array focusing	215
5.4.8	Interferometry	216
5.4.9	Advanced goniometric detection	221
5.4.10	High-resolution methods vs. beamforming	223
6	Sonar Signal Processing – Principles and Performance	225
6.1	Introduction	225
6.2	Preliminary notions	226
6.2.1	Signal design	226
6.2.2	Signal-to-noise ratio (SNR)	234
6.3	Passive sonar signal processing	237
6.3.1	Non-coherent detection	237
6.3.2	Broadband detection performance	238
6.3.3	Narrowband detection performance	239
6.3.4	Other operations in passive sonar processing	240
6.4	Active sonar signal processing	241
6.4.1	Narrowband pulse signals	241
6.4.2	Frequency modulated pulse (<i>chirp</i>)	244
6.4.3	Phase-modulated signals	248
6.5	Structure of sonar receivers	250
6.5.1	Typical sonar receiver	250
6.5.2	Time-varying Gain (TVG)	251

6.5.3	Signal demodulation	253
6.5.4	Matched filtering	254
6.6	Sonar system performance	255
6.6.1	The sonar equation	255
6.6.2	Notes about the reception threshold	256
6.6.3	Performance in detection	257
6.6.4	Performance of underwater acoustic communication systems	263
6.6.5	Parameter estimation errors	267
7	Water Column Applications	271
7.1	Navigation	271
7.1.1	Acoustic beacons	271
7.1.2	Echosounding	273
7.1.3	Speed measurements	275
7.1.4	Obstacle avoidance	276
7.2	Military applications	277
7.2.1	An historical perspective: ASDIC systems	277
7.2.2	Passive sonars	278
7.2.3	Active sonars	285
7.3	Fishery acoustics	291
7.3.1	Fishery sounders	291
7.3.2	Panoramic sonars	294
7.3.3	Other acoustic equipment of fishing vessels	295
7.3.4	Fishery multibeam echosounders	295
7.3.5	Scientific applications of fishery sonars	297
7.4	Physical oceanography	299
7.4.1	Doppler current profilers	299
7.4.2	Ocean acoustic tomography	308
7.4.3	Global acoustics	311
7.4.4	Other applications of SOFAR propagation	313
7.5	Underwater intervention	313
7.5.1	Acoustic positioning	313
7.5.2	Underwater acoustic communication	316
8	Seafloor-mapping sonar systems	323
8.1	Single-beam sounders	324
8.1.1	Overview	324
8.1.2	Performance and limitations of single-beam sounders	328
8.2	Sidescan sonars	336
8.2.1	Overview	336
8.2.2	Performance and limitations of sidescan sonars	343
8.2.3	Measuring bathymetry with a sidescan sonar	345
8.2.4	Synthetic aperture sonar	346
8.3	Multibeam echosounders	351
8.3.1	Overview	351
8.3.2	Multibeam echosounder structure	353

8.3.3	Bathymetry measurements	357
8.3.4	Sonar imaging with multibeam sounders	362
8.3.5	Performance of multibeam sounders.	363
9	Sub-bottom Investigation	371
9.1	Sediment profilers	372
9.1.1	Overview	373
9.1.2	Sediment profiler performances	376
9.1.3	Echo formation and consequences	378
9.1.4	Three original concepts of sediment profilers	379
9.2	Marine seismic exploration	383
9.2.1	General principles.	383
9.2.2	Marine seismic technology.	386
9.3	Reflection seismic surveys	393
9.3.1	Acquisition configuration	394
9.3.2	Physical context: propagation and reflection phenomena	399
9.4	Seismic processing principles	407
9.4.1	Seismic processing overview.	407
9.4.2	Recorded signal	409
9.4.3	Preprocessing	409
9.4.4	Velocity analyses, NMO and stack.	411
9.4.5	Migration	417
9.4.6	Amplitude processing	421
9.5	Seismic vs. sonar investigation	422
10	Marine Animal Acoustics	425
10.1	Marine mammal bioacoustics	425
10.1.1	Sound reception	426
10.1.2	Hearing performance.	430
10.1.3	Sounds produced by toothed whales	436
10.1.4	Sound generation mechanisms of toothed whales.	438
10.1.5	Sounds produced by baleen whales.	439
10.1.6	Sound production mechanisms of baleen whales	441
10.1.7	Sounds produced by pinnipeds	441
10.1.8	Sound production mechanisms of pinnipeds	443
10.1.9	Sounds produced by manatees and dugongs	444
10.1.10	Sound production mechanisms of manatees and dugongs.	444
10.2	Fish bioacoustics.	444
10.2.1	Sound reproduction by fishes	444
10.2.2	Fish hearing performance	446
10.2.3	Sound production by fishes	448
10.3	Marine turtle, snake, and seabird acoustics	449
10.4	Invertebrate bioacoustics	451
10.4.1	Invertebrate sound reception	451
10.4.2	Sound production by invertebrates	452

10.5	Acoustic pollution of the ocean	453
10.5.1	Overview	453
10.5.2	Sound-mediated injury to animals	454
10.5.3	Other physiological and behavioral effects of noise on animals	455
10.5.4	Effects of high-powered sonar on animals	456
10.5.5	Effects of airguns on marine animals	460
10.5.6	Acoustic deterrent devices	463
10.5.7	Effects of other active acoustic devices on animals	465
10.5.8	Effects of incidental sources and ambient noise on marine animals	466
10.5.9	The challenge of understanding and regulating noise pollution	468
10.5.10	Mitigating negative impacts of anthropogenic sound	470
10.6	Summary	472
11	Conclusion	475
11.1	Synthesis	475
11.1.1	Propagation	475
11.1.2	Reflection and backscattering	476
11.1.3	Noise and fluctuations	477
11.1.4	Transducers and array processing	478
11.1.5	Signal processing	479
11.1.6	Marine life and acoustics	480
11.2	Current trends and perspectives	481
11.2.1	A major tool for monitoring and exploitation of the Earth	481
11.2.2	Underwater acoustics in perspective	482
	Appendices	487
A.1.1	The units of underwater acoustics	487
A.1.2	Basic logarithmic formulas	490
A.1.3	The cardinal sine function	491
A.2.1	The average intensity model	492
A.2.2	Fundamental derivations of geometrical acoustics	494
A.2.3	Normal modes in isovelocity configurations	500
A.3.1	Fluid interface reflection coefficients	503
A.3.2	Simplified models of biological target strength	506
A.3.3	Coherent reflections on a rough interface	508
A.3.4	A heuristical model for seafloor backscattering	509
A.4.1	Self-noise level of an oceanographic vessel: A case study	510
A.4.2	Radiation pattern of a dipole	512
A.5.1	Basics of piezoelectricity	514
A.5.2	Parametric arrays	517
A.5.3	Electro-acoustic analogies	518

xii **Contents**

A.5.4	Directivity pattern of a line array	521
A.5.5	Directivity pattern of a curved array	524
A.5.6	Array shading performance.	525
A.5.7	Interferometry	527
A.5.8	High-resolution methods in array processing	530
A.6.1	Fourier transform: Main properties	535
A.6.2	Analogue receivers for narrow-band pulses and processing gain.	536
A.7.1	Channel capacity for digital transmissions	537
A.8.1	Contrast of seafloor sonar images	539
A.9.1	Seismic wave propagation.	540
A.10.1	Sounds produced by marine mammals.	546
A.10.2	Examples of sounds produced by fishes	560
	The sonar equations	563
	Exercises and problems.	571
	Numerical results.	593
	References	605
	Index	669



<http://www.springer.com/978-3-540-78480-7>

An Introduction to Underwater Acoustics
Principles and Applications

Lurton, X.

2010, XXXVI, 680 p., Hardcover

ISBN: 978-3-540-78480-7