## Contents

1. **Review of Recent Advances on Reactionless Mechanisms and Parallel Robots** ......................................................... 1  
   Dan Zhang and Bin Wei

2. **Design of Reactionless Mechanisms Without Counter-rotations** ...... 21  
   Vlastimil Votrubec

3. **Design of Reactionless Linkages and Robots Equipped with Balancing Assur Groups** ............................................. 33  
   Sébastien Briot and Vigen Arakelian

4. **Design of Reactionless Planar Parallel Manipulators with Inertia Flywheel or with Base-Mounted Counter-rotations** ...... 69  
   Vigen Arakelian

5. **Design of Reactionless Mechanisms with Counter-Rotary Counter-Masses** ............................................................... 83  
   Mario Acevedo

6. **Shaking Force and Shaking Moment Balancing of Six- and Eight-Bar Planar Mechanisms** ................................. 113  
   Peddinti Nehemiah

7. **Synthesizing of Parallel Robots Using Adjusting Kinematic Parameters Method** ........................................................ 143  
   P.R. Ouyang, W.J. Zhang, and J. Huang

8. **Balancing of a 3-DOFs Parallel Manipulator** ........................... 173  
   D. Cafolla, G. Carbone, and M. Ceccarelli

9. **Dynamic Balancing with Respect to a Given Trajectory** .............. 193  
   Taizo Yoshikawa
10 Dynamic Balancing and Flexible Task Execution for Dynamic Bipedal Walking Machines ................................. 229
Andreas Hofmann

11 Design of Reactionless Mechanisms Based on Constrained Optimization Procedure ................................................... 273
Himanshu Chaudhary and Kailash Chaudhary

12 Balancing of Planar Mechanisms Having Imperfect Joints Using Neural Network-Genetic Algorithm (NN-GA) Approach ...... 299
Selçuk Erkaya and İbrahim Uzmay

13 Minimization of Shaking Force and Moment on a Four-Bar Mechanism Using Genetic Algorithm .................................................. 319
Selçuk Erkaya

14 Optimal Balancing of the Robotic Manipulators .............................. 337
A. Nikoobin and M. Moradi

15 Dynamics and Control of Planar, Translational, and Spherical Parallel Manipulators ...................................................... 365
Victor Glazunov and Sergey Kheylo

16 Dynamic Modelling and Control of Balanced Parallel Mechanisms . 403
Renato Maia Matarazzo Orsino, André Garnier Coutinho, and Tarcisio Antonio Hess Coelho

17 Controlled Biped Balanced Locomotion and Climbing ............... 447
Benjamin Kenwright

18 Dynamic Balancing of Mobile Robots in Simulation and Real Environments ............................................................... 457
Adrian Boeing and Thomas Bräunl

19 Balancing Conditions of Planar and Spatial Mechanisms in the Algebraic Form ......................................................... 475
Nguyen Van Khang and Nguyen Phong Dien

20 Static Balancing of Articulated Wheeled Vehicles by Parallelogram- and Spring-Based Compensation .......................... 513
Aliakbar Alamdari and Venkat Krovi