Contents

Kinematic and Workspace-Based Synthesis of a 2-DOF Mechanism for Haptic Applications ........................................... 1 R. Roberts and E. Rodriguez-Leal

Fuzzy Logic Control on FPGA for Solar Tracking System ............... 11 Ricardo Antonio-Mendez, Jesus de la Cruz-Alejo and Ollin Peñaloza-Mejia

Dynamic Balancing of a Nutating Planetary Bevel Gear Train .......... 23 P. Fanghella, L. Bruzzone and S. Ellero

Output Stabilization of Linear Systems with Disturbances ............... 35 Francisco Javier Bejarano and Jorge Dávila

Development of a Heliostat for a Solar Tower Power Plant ............. 45 Jorge A. García Pitol, Alicia Hernandez Gutierrez, Manuel Toledano Ayala, Juan C.A. Jáuregui Correa, Enma V. Godoy Avendaño and Oswaldo Mendoza Herbert

Mechatronic Sizing of Ball-Screw Feed Drives .......................... 55 R. Hecker, D. Vicente and G. Flores

Behavior of the Robot with Vibratory Excitation ........................ 67 T. Majewski and D. Szwedowicz

Attitude Determination System Based on Vector Observations for Satellites Experiencing Sun-Eclipse Phases .................... 75 J. Rodrigo Cordova-Alarcon, Mario A. Mendoza-Barcenas and Arturo Solis-Santome
Contents

Nonlinear Identification of Inverted Pendulum System
Using Volterra Polynomials ........................................ 87
G. Ronquillo, G.J. Ríos Moreno, E. Hernández Martínez
and M. Trejo Perea

Multi-robot Exploration and Mapping Strategy in Underground
Mines by Behavior Control ........................................ 101
Antoni Mauricio, Ayrton Nieves, Yomar Castillo, Kenji Hilasaca,
Christian Fonseca, Jhair Gallardo, Ricardo Rodríguez
and Glen Rodríguez

Modeling Online via Clustering and Fuzzy SVM. .................. 111
J.C. Tovar, C.R. Mariaca and I. Álvarez Villalobos

Cylindrical Contact Force Models for the Dynamics
of Roller Chain Drives ............................................ 121
J. Ambrosio, C. Malça and A. Ramalho

A Three-Dimensional Multibody Model of a Full Suspension
Mountain Bike ...................................................... 133
B. Corves, J. Breuer, F. Schoeler and P. Ingenlath

Gear Shifting Strategies Co-simulations to Optimize Vehicle
Performance and Fuel Consumption ............................. 143
Jony J. Eckert, Fernanda C. Corrêa, Fabio M. Santiciolli,
Eduardo S. Costa, Heron J. Dionisio and Franco G. Dedini

Vibration Analysis of an Offshore Platform-Like Structure
Excited by Earthquake .............................................. 153
J. Enriquez-Zárate and G. Silva-Navarro

Dynamic Parameter Identification in the Front Suspension
of a Vehicle: On the Influence of Different Base Parameter Sets .... 165
L.A. Mejía, V. Mata, F. Valero, J. Ros and X. Iriarte

An Alternative Method for the Optimum Dynamic Balancing
of the Four-Bar Mechanism ...................................... 177
Mario Acevedo, Eduardo Haro and Félix Martinez

Behavior of Some Objects in Series with Dynamic Eliminators
of Vibrations ...................................................... 189
Tadeusz Majewski
Modeling, Analysis and Simulation of 3D Elastohydrodynamic Revolute Joints in Multibody Systems. .............................. 199
P. Flores

Analysis of Experimental Data from Complex Multibody System ............................................................. 211
J.C. Jáuregui-Correa, C.S. López Cajún and Mihir Sen

Reduced Energy Consumption in Induction Motors with Possible Mechatronic Applications ....................... 219
G. Calzada-Lara and J. Álvarez-Gallegos

Modeling and Control of a Pendubot with Static Friction ............. 229
Sergio Sánchez-Mazuca, Israel Soto and Ricardo Campa

Design of Electronic Control Board to Obtain the Photovoltaic Module Power Voltage Curve as Temperature Function .......... 241
J. Vega-Pérez, S. Vega-Pérez and L. Castañeda-Aviña

A Robust Control Scheme Against Some Parametric Uncertainties for the NXT Ballbot .................................. 249
R.A. García-García and M. Arias-Montiel

Fuzzy Logic Control on FPGA Using LabVIEW ...................... 261
Juan Carlos García-Montalva, Jesús de la Cruz-Alejo and Jorge Diaz-Salgado

High-Order Sliding Modes Based Linearization: An Application to Roll Autopilot .................................................. 273
J. Davila, A. Monsivais and A. Mosqueda

Proposal of Automated Inspection Using Camera in Process of VIN Validation ............................................. 285
L.R.S. Souza, R.M.M. Oliveira and M.H. Stoppa

Concept Design Process for Robotic Devices: The Case of an Assistive Robot ................................................. 295
H.A. Moreno Avalos, I.G. Carrera Calderón, S. Romero Hernández and V. Cruz Morales

Design and Construction of a Submarine with Five Degrees of Freedom ......................................................... 305
Ortiz R. Floriberto, Barroeta Z. Carlos and J. Francisco Novoa C
Concurrent Structure-Control Design of Parallel Robots
Using an Estimation of Distribution Algorithm
E. Chávez-Conde, S. Ivvan Valdez and Eusebio Hernández

315

Emulation of Mechanical Structures Through a Multi-agent
Robot System: An Overview
J. González-Sierra and E. Aranda-Bricaire

327

Design and Construction of a Nouvelle Vertical Axis Wind
Turbine Experimental Platform
Lourdes García, David Lara, Azahel Treviño, Gerardo Romero,
José G. Rivera and Esmeralda López

339

Motion Analysis of a Six-Legged Robot Using the Bennett’s
Linkage as Leg
J.C.M. Carvalho and T.R. Silvestre

349

Implementation of Force and Position Controllers
for a 3DOF Parallel Manipulator
J. Cazalilla, M. Vallés, A. Valera, V. Mata and M. Díaz-Rodríguez

359

Mechanical Reproduction of the Horse Movement
from a Hippotherapy Cycle
C.S. López-Cajún, J.C. Jáuregui-Correa, C.A. González-Cruz
and M. Rodríguez

371

Identification of a Cylindrical Robot Using Recurrent Neural
Networks.
Carlos Román Mariaca Gaspar, Juan Eduardo Velázquez-Velázquez
and Julio César Tovar Rodríguez

381

New Design of Petal Type Deployable Space Mirror
V.I. Bujakas

391

Corradino D’Ascanio and His Design of Vespa Scooter
M. Ceccarelli and G. Teoli

399

Rigid Body Hyper-jerk Analysis Using Screw Theory
Jaime Gallardo-Alvarado and Mario A. García-Murillo

411

Joint Trajectory Optimization Using All Solutions of Inverse
Kinematics of General 6-R Robots
U. Kuenzer and M.L. Husty

423
## Contents

<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mill Setup Manual Aided by Augmented Reality</td>
<td>433</td>
</tr>
<tr>
<td>F. Suárez-Warden, E. González Mendivil, H. Ramírez, L.E. Garza Nájera and G. Pantoja</td>
<td></td>
</tr>
<tr>
<td>Dimensional Synthesis of a Planar Parallel’ Manipulator Applied to Upper Limb Rehabilitation</td>
<td>443</td>
</tr>
<tr>
<td>Ileana P. Corona-Acosta and Eduardo Castillo-Castaneda</td>
<td></td>
</tr>
<tr>
<td>Workspace Analysis of a Delta-Like Robot Using an Alternative Approach</td>
<td>453</td>
</tr>
<tr>
<td>A. Gutiérrez-Preciado, M.A. González-Palacios and L.A. Aguilera-Cortés</td>
<td></td>
</tr>
<tr>
<td>Adaptive Low Cost Gravity Balanced Orthosis</td>
<td>465</td>
</tr>
<tr>
<td>Giuseppe Cannella, Dina S. Laila and Christopher T. Freeman</td>
<td></td>
</tr>
<tr>
<td>Design and FEM Analysis of a Novel Humanoid Torso</td>
<td>477</td>
</tr>
<tr>
<td>Daniele Cafolla and Marco Ceccarelli</td>
<td></td>
</tr>
<tr>
<td>Nonlinear Full-Car Model for Optimal Dynamic Design of an Automotive Damper</td>
<td>489</td>
</tr>
<tr>
<td>Carlos A. Duchanoy, Carlos A. Cruz-Villar and Marco A. Moreno-Armendáriz</td>
<td></td>
</tr>
<tr>
<td>Design of a Parallel Mechanism for Knee Rehabilitation</td>
<td>501</td>
</tr>
<tr>
<td>B.D. Chaparro-Rico, E. Castillo-Castaneda and R. Maldonado-Echegoyen</td>
<td></td>
</tr>
<tr>
<td>Design and Construction of a Translational Parallel Robot for Drilling Tasks</td>
<td>511</td>
</tr>
<tr>
<td>R. Maldonado-Echegoyen and E. Castillo-Castaneda</td>
<td></td>
</tr>
<tr>
<td>A Solution to the Approximate Spherical Burmester Problem</td>
<td>521</td>
</tr>
<tr>
<td>Jérémie Léger and Jorge Angeles</td>
<td></td>
</tr>
<tr>
<td>Mechatronic Design of a Mobile Robot and Non-Linear Control</td>
<td>531</td>
</tr>
<tr>
<td>J. Hernández, J. Torres and S. Salazar</td>
<td></td>
</tr>
<tr>
<td>Decentralized Supervisory Control of an AMS Based on the ISA Standards</td>
<td>543</td>
</tr>
<tr>
<td>E.G. Hernandez-Martinez, S.A. Foyo-Valdes, E.S. Puga-Velazquez and J.A. Meda-Campaña</td>
<td></td>
</tr>
</tbody>
</table>
A Planar Cobot Modelled as a Differential Algebraic System .......... 555
Omar Mendoza-Trejo and Carlos Alberto Cruz-Villar

Design and Implementation of an Affective Computing for Recognition and Generation of Behaviors in a Robot .......... 567
Rodolfo Romero Herrera, Francisco Gallegos Funes and Maria Adela Soto Alvarez del Castillo

Author Index ........................................ 579
Multibody Mechatronic Systems
Proceedings of the MUSME Conference held in Huatulco, Mexico, October 21-24, 2014
Ceccarelli, M.; Hernandez, E. (Eds.)
2015, XIV, 581 p. 360 illus., Hardcover
ISBN: 978-3-319-09857-9