

# Contents

## Part I Theoretical Kinematics

<b>Dimensional Synthesis of Six-Bar Linkages with Incomplete Data Set</b> . . . . .	3
Shaoping Bai	
<b>Mathematical Modelling and Simulation for Beaded Pad Automatic Weaving Trajectory</b> . . . . .	13
Jianye Yan, Ligang Yao, Dongliang Lin and Zhijun Liu	
<b>Graphical User Interface for the Singularity Analysis of Lower-Mobility Parallel Manipulators</b> . . . . .	21
Stéphane Caro, Latifah Nurahmi and Philippe Wenger	
<b>On the Redundancy of Cable-Driven Parallel Robots</b> . . . . .	31
J.-P. Merlet	

## Part II Computational Kinematics

<b>On the Resolution of Forward Kinematic Problem Using CAD Graphical Techniques: Application on Planar Parallel Robotic Manipulators</b> . . . . .	43
K.A. Arrouk, B.C. Bouzgarrou and G. Gogu	
<b>Introducing Distance Restrictions in the Deformed Position Problem</b> . . . . .	53
I. Fernández de Bustos, V. García Marina, M. Abásolo and R. Avilés	
<b>On Generalized Euler Angles</b> . . . . .	61
Aleix Rull and Federico Thomas	

<b>Guaranteed Detection of the Singularities of 3R Robotic Manipulators . . . . .</b>	<b>69</b>
Romain Benoit, Nicolas Delanoue, Sébastien Lagrange and Philippe Wenger	
<b>Workspace Analysis for Evaluating Laparoscopic Instruments . . . . .</b>	<b>81</b>
J.-H. Borchard, F. Dierßen, J. Kotlarski, L.A. Kahrs and T. Ortmaier	
<b>A Novel, Loop-Based Approach for Rigidity Detection for Systems with Multiple Spherical–Spherical Bars: The “Double-Banana” Case . . . . .</b>	<b>91</b>
F. Simroth, H.F. Ding and A. Kecskeméthy	
<b>Planar Four-Link Mechanism Analysis for Application in 3D Printing Machines . . . . .</b>	<b>99</b>
A. Kłodowski	
<b>Part III Mechanism Design</b>	
<b>Path Generating Belt Mechanisms as Kinematic Chains for Mechatronic Applications . . . . .</b>	<b>111</b>
E.-C. Lovasz, D. Perju, K.-H. Modler, C.M. Gruescu, D. Mărgineanu, C.E. Moldovan and C. Pop	
<b>Synthesis of a Mechanism for Human Gait Rehabilitation: An Introductory Approach . . . . .</b>	<b>121</b>
Pedro Alves, Francisco Cruz, Luís F. Silva and Paulo Flores	
<b>A Form-Closed Cam-Follower Mechanism for a Breath Simulator Machine . . . . .</b>	<b>129</b>
R.F. Oliveira, P. Flores, S.F. Teixeira, H.M.C. Marques and J.C. Teixeira	
<b>Dimensional Synthesis with Mechanism Processing Strategy . . . . .</b>	<b>139</b>
M. Hüsing, R. Braune and B. Corves	
<b>Dynamic Modelling of a Four Legged Robot. . . . .</b>	<b>147</b>
I. Geonea, A. Ungureanu, N. Dumitru and L. Racilă	
<b>Lifting Mechanism for Payload Transport by Collaborative Mobile Robots. . . . .</b>	<b>157</b>
B. Hichri, J.-C. Fauroux, L. Adouane, I. Doroftei and Y. Mezouar	

<b>Kinematic Design of a Reconfigurable Deployable Canopy . . . . .</b>	167
G. Kiper, F. Gürcü, K. Korkmaz and E. Söylemez	
<b>Function Generation Synthesis with a 2-DoF Overconstrained Double-Spherical 7R Mechanism Using the Method of Decomposition and Least Squares Approximation. . . . .</b>	175
G. Kiper and B. Bağdadioğlu	
<b>Designing Cam Mechanisms Using CAx . . . . .</b>	185
J. Ondrášek	
<b>Kinematics Analysis and Verification on the Novel Reconfigurable Ankle Rehabilitation Robot Based on Parallel Mechanism. . . . .</b>	195
Shilong Zeng, Ligang Yao, Xiaoning Guo, Hengli Wang and Pengju Sui	
<b>Finite Element Modeling and Analysis of an Isoglide-Type Parallel Manipulator to Determine Its Rigidity/Stiffness. . . . .</b>	203
A. Kozyrev and V. Glazunov	
<b>Modular Cooperative Mobile Robots for Ventral Long Payload Transport and Obstacle Crossing . . . . .</b>	211
M. Krid, J.C. Fauroux and B.C. Bouzgarrou	
<b>Hypo-Cycloidal Crank Mechanism to Produce an Over-Expanded Cycle Engine . . . . .</b>	221
J. Pinto, T. Costa, J. Martins and F.P. Brito	
 <b>Part IV Experimental Mechanics</b>	
<b>Influence of the Mass of the Weight on the Dynamic Response of the Laboratory Fibre-Driven Mechanical System . . . . .</b>	233
P. Polach and M. Hajžman	
<b>On the Experimental Intradiscal Pressure Measurement Techniques: A Review . . . . .</b>	243
A. Araújo, N. Peixinho, A. Pinho and J.C.P. Claro	
<b>Geometry and Material Strategies for Improved Management of Crash Energy Absorption . . . . .</b>	251
N. Peixinho	

<b>An In Vitro Experimental Evaluation of the Displacement Field in an Intracranial Aneurysm Model. . . . .</b>	261
Diana Pinho, David Bento, João Ribeiro, Rui Lima and Mário Vaz	
<b>Experiments on the Edge of Chaos of a Planar Closed Chain Underactuated Mechanism. . . . .</b>	269
J. Xie, H. Zhao, Z.-H. Liu and Y. Chen	
<b>Systematic and Rapid Construction of Test Beds for Planar Mechanism . . . . .</b>	277
H. Mencek and R. Soylu	
<b>Development of Impact Loading Equipment for Testing of FRP Strips as Reinforcement of Masonry Bricks. . . . .</b>	287
P. Correia and N. Peixinho	
 <b>Part V Mechanics of Robots</b>	
<b>Design of a Driving Module for a Hybrid Locomotion Robot. . . . .</b>	299
J.J. Castillo, J.A. Cabrera, M. Jaimez, F. Vidal and A. Simón	
<b>Analysis of Joint Clearance Effects on Dynamics of Six DOF Robot Manipulators . . . . .</b>	307
S. Erkaya	
<b>Investigating the Effect of Cable Force on Winch Winding Accuracy for Cable-Driven Parallel Robots. . . . .</b>	315
Valentin Schmidt, Alexander Mall and Andreas Pott	
<b>Solving the Dynamic Equations of a 3-PRS Parallel Manipulator. . . . .</b>	325
M. Díaz-Rodríguez, R. Bautista-Quintero and J.A. Carretero	
 <b>Part VI Dynamics of Machinery</b>	
<b>Optimization of Textile Machines in Order to Increase Productivity . . . . .</b>	337
B. Corves, M. Hüsing, M. Schumacher and F. Schwarzfischer	
<b>Motion Equation of Linkages with Changeable Close Loop. . . . .</b>	345
E. Gebel	

**Elastodynamic Analysis of the Sucker Rod Pumping System Mechanism . . . . .** 355  
 N. Dumitru, N. Craciunoiu, R. Malciu and N. Ploscaru

**Dimensioning the NC: Axes of a Radial Cam Grinding Machine . . . . .** 365  
 V. Crhák, P. Jirásko and M. Václavík

**Efficiency Analysis of Shifted Spur Gear Transmissions. . . . .** 373  
 A. Diez-Ibarbia, A. Fernández del Rincón, M. Iglesias, A. De Juan, P. García and F. Viadero

**Part VII Dynamics of Multi-body Systems**

**A New Approach to Eliminate the Constraints Violation at the Position and Velocity Levels in Constrained Mechanical Multibody Systems . . . . .** 385  
 P. Flores

**Vehicle Dynamic Simulation Using Robotic Techniques and Taking into Account a Tyre Model . . . . .** 395  
 B. Menkouz and M. Haddad

**An Advanced 3D Multi-body System Model for the Human Lumbar Spine . . . . .** 405  
 S. Sousa and J.C.P. Claro

**Energy-Consistent Integration Scheme for Multi-body Systems with Dissipation . . . . .** 413  
 S. Conde Martín and J.C. García Orden

**Multi-objective Optimization of Mechanisms with Clearances in Revolute Joints . . . . .** 423  
 Z. Zhang, L. Xu, Y.Y. Tay, P. Flores and H. Lankarani

**Biomechanical Experimental Data Curation: An Example for Main Lumbar Spine Ligaments Characterization for a MBS Spine Model . . . . .** 435  
 C. Lourenço and J.C.P. Claro

**A Three-Dimensional Multibody Model of the Human Ankle-Foot Complex . . . . .** 445  
 T.M. Malaquias, S.B. Gonçalves and M. Tavares da Silva

<b>Inverse Dynamics of 2-DOF Parallel Mechanism Used for Orientation</b> . . . . .	455
T. Itul, B. Gherman, D. Cocorean and D. Pisla	
<b>Wear Prediction of Ceramic-on-Ceramic Artificial Hip Joints</b> . . . . .	463
E. Askari, P. Flores, D. Dabirrahmani and R. Appleyard	
<b>Techniques for Geometrical Detection of Contact Within Multibody Systems</b> . . . . .	471
M. Machado, P. Flores and J. Ambrósio	
<b>On the Equivalence Between Forward and Inverse Dynamic Analysis of Human Motion Tasks.</b> . . . . .	479
C. Quental, J. Folgado, J. Ambrósio and J. Monteiro	
<b>Railway Vehicle Modelling for the Vehicle-Track Interaction Compatibility Analysis.</b> . . . . .	487
H. Magalhães, J. Ambrósio and J. Pombo	
<b>Validation of an Enhanced Cylindrical Contact Force Model Using Numerical and Analytical Approaches.</b> . . . . .	497
C. Pereira, A. Ramalho and J. Ambrosio	
<b>Human Gait Analyses Using Multibody Systems Formulation: Normal and Pathological Scenarios</b> . . . . .	505
P. Moreira, J. Peixoto, U. Lúgrís, J. Cuadrado, P. Flores and P. Souto	
<b>Numerical Simulation of a Granular Material Damper</b> . . . . .	515
T. Koga, T. Sato, A. Weller and K. Ono	
<b>Wagon Multibody Model and Its Real-Time Application.</b> . . . . .	523
M. Spiryagin, S.S.N. Ahmad, C. Cole, Y.Q. Sun and Tim McSweeney	
<b>Part VIII Control Issues of Mechanical Systems</b>	
<b>Experimental Validation of the Mechatronic Model of a Parallel Manipulator</b> . . . . .	535
O. Altuzarra, F.J. Campa, C. Roldan-Paraponiaris and Ch. Pinto	
<b>Preferable Operation Modes of a Wind Turbine with a Differential Planetary Gearbox.</b> . . . . .	545
M. Dosaev, A. Holub and L. Klimina	

**Hybrid Position/Force Control of a Cable-Driven Parallel Robot with Experimental Evaluation . . . . .** 553  
 Werner Kraus, Philipp Miermeister, Valentin Schmidt and Andreas Pott

**The Control System of a Parallel Robot for Brachytherapy . . . . .** 563  
 C. Vaida, D. Pislă, A. Szilaghyi, F. Covaciu, D. Cocorean and N. Plitea

**Ambient Assisted Living Platform for Remote Monitoring of Bedridden People . . . . .** 573  
 F. Pereira, C. Barros, V. Carvalho, J. Machado, C.P. Leão, F. Soares, K. Bezerra and D. Matos

**Part IX Mechanisms for Biomechanics**

**Design and Simulation of Humanoid Spine . . . . .** 585  
 Daniele Cafolla and Ceccarelli Marco

**Feet Compliance in Two Legged Locomotion . . . . .** 595  
 Magdalena Zurawska and Teresa Zielinska

**Lab Experiences with LARM Clutched Arm for Assisting Disabled People . . . . .** 603  
 C. Copilusi, M. Kaur and M. Ceccarelli

**Design and Simulation of Walking Operation of a Cassino Biped Locomotor . . . . .** 613  
 Mingfeng Wang and Marco Ceccarelli

**Pneumatic Video Tactile Sensor for Laparoscopic Surgery . . . . .** 623  
 M. Dosaev, I. Goryacheva, F.-C. Su, C.-H. Yeh, M.-S. Ju, M. Gubenko, A. Lyubicheva, A. Morozov and Yu Selyutskiy

**Design of a New Medical Device for Aiding Clinical Diagnosis of Patellofemoral Disorders . . . . .** 633  
 A. Leal, R. Pereira, H. Pereira, P. Flores, F.S. Silva and J. Espregueira-Mendes

**Lab Experiences with a Linkage Exoskeleton for Walking Assistance . . . . .** 643  
 I. Silva, M. Ceccarelli, C. Copilusi and P. Flores

**Characterization and Analysis of Data in Autistic Walk Pressure . . . .** 651  
 L. Souza, S. Rosa, M. Carvalho and T. Torquato

<b>Physiological-Like Testing of the Dislocation Stability of Artificial Hip Joints</b> . . . . .	659
S. Herrmann, M. Kähler, R. Grawe, D. Kluess, C. Woernle and R. Bader	
<b>Experimental Bench Used to Test Human Elbow Endoprosthesis</b> . . . . .	669
D. Tarnita, D. Popa, C. Boborelu, N. Dumitru, D. Calafeteanu and D.N. Tarnita	
<b>A Dynamic Intramedullary Implant for Bone Fracture Repair</b> . . . . .	679
A. Dowd, B.J. Mac Donald, R. Lostado, W.T. McCartney and D. Comiskey	
<b>A Computational Benchmark for 2D Gait Analysis Problems</b> . . . . .	689
R. Pàmies-Vilà, J.M. Font-Llagunes, U. Lugrís, F.J. Alonso and J. Cuadrado	
<b>Development and Early Results of a New Concept of an Orthopedic Footwear Stirrup</b> . . . . .	699
J. Peixoto, B. Moura, P. Moreira, A.P. Souto and P. Flores	
<b>Dynamic Analysis of an Exoskeleton New Ankle Joint Mechanism</b> . . . . .	709
N. Dumitru, C. Copilusi, I. Geonea, D. Tarnita and I. Dumitrache	
<b>Part X Novel Designs</b>	
<b>Analysing of Flying Conditions of Aircrafts Using Artificial Neural Networks</b> . . . . .	721
Ş. Yıldırım and S. Erkaya	
<b>Digital-Based Engineering Tools for Tailored Design of Medical Implants</b> . . . . .	733
R. Neto, T. Marques, M. Marta, N. Leal, M. Couto and M. Machado	
<b>Synthesis of PR/RP-Chain Based Compliant Mechanisms: Design of Applications Exploiting Fibre Reinforced Material Characteristics</b> . . . . .	743
U. Hanke, E.-C. Lovasz, M. Zichner, N. Modler, A. Comsa and K.-H. Modler	
<b>Computer and Physical Simulation of Space Mirror Deployment</b> . . . . .	755
V.I. Bujakas	



**Permeability Evaluation of Flow Behaviors Within Perfusion Bioreactors** . . . . . 761  
 D. Freitas, H.A. Almeida and P.J. Bártolo

**Part XI Mechanical Transmissions**

**Load Sharing and Contact Stress Calculation of High Contact Ratio Internal Spur Gears** . . . . . 771  
 M. Pleguezuelos, J.I. Pedrero and M.B. Sánchez

**Calculation of Load Capacity of Cylindrical Gears: Review of Different Approaches and Calculation Tools** . . . . . 779  
 S.M.O. Tavares and P.M.S.T. de Castro

**Load Distribution in Spur Gears Including the Effects of Friction** . . . . . 789  
 Pedro M.T. Marques, Ramiro C. Martins and Jorge H.O. Seabra

**Influence of Gear Loss Factor on the Power Loss Prediction** . . . . . 799  
 Carlos M.C.G. Fernandes, Pedro M. T. Marques, Ramiro C. Martins and Jorge H. O. Seabra

**Hydraulic Hose as an Instability Reducer for a Flexible Shaft Composed by Universal Joints** . . . . . 807  
 V.H. Carneiro and J. Meireles

**Propulsion Architectures Using Mechanical Energy Storage** . . . . . 817  
 Madhusudan Raghavan

**Part XII Linkages and Manipulators**

**Closed-Chain Principal Vector Linkages** . . . . . 829  
 V. van der Wijk

**Design of a Low-Cost Manipulator Arm for Industrial Fields** . . . . . 839  
 E. Soriano, H. Rubio, C. Castejón and J.C. García-Prada

**Part XIII Micro-Mechanisms**

**A New Pseudo-Rigid-Body Model of Compliant Mechanisms Considering Axial Deflection of Flexural Beams** . . . . . 851  
 Yue-Qing Yu, Peng Zhou and Qi-Ping Xu

**An Internal Gyroscopic Micro-Mechanism for Development of Lateral Deviation of a Projectile** . . . . . 859  
 C.M. Umstead, Y.Y. Tay and H.M. Lankarani

**An Approach to the Characterization of Flexure Hinges for the Purpose of Optimizing the Design of a Micromanipulator** . . . . 869  
 D. Schoenen, I. Ivanov and B. Corves

**Part XIV Teaching Methods**

**Machine and Mechanism Design at UMinho: Research-Teaching Interaction** . . . . . 881  
 M. Lima, E. Seabra and L.F. Silva

**Computer Aided, Task-Based Kinematic Design of Linkages: A New Lecture for Engineering Students** . . . . . 891  
 K. Abdul-Sater, T.C. Lueth and F. Irlinger

**Part XV History of Mechanism Science**

**A.N. Krylov: The Pioneer of Photographic Non-invasive Measurement Methods in Russian Science** . . . . . 903  
 Andrei Vukolov and Alexander Golovin

**Animation of Historical Patents** . . . . . 913  
 U. Döring, C. Brandt-Salloum, V. Henkel and T. Brix

**Part XVI Industrial and Non-industrial Applications**

**Dynamic Modeling and Analysis of an Industrial Cutting File Machine** . . . . . 923  
 E. Seabra, Luís F. Silva and P. Flores

**An Overview of Industrial Communication Networks** . . . . . 933  
 M. Silva, F. Pereira, F. Soares, C.P. Leão, J. Machado and V. Carvalho

**Rapid Development of Control Algorithms and Interfaces for Remote Monitoring of Robotic Arm Through Internet of Things (IoT)** . . . . . 941  
 M. Murar and S. Brad

**Numerical Simulation of Impact Loading on Open-Cell Aluminum Foams** . . . . . 949  
P. Moreira, J.P. Mendonça and N. Peixinho

**Combining the Finite Element Method and Response Surface Methodology for Adjustment of Contact Stress Ratios in Tapered Roller Bearings** . . . . . 957  
R. Lostado, R. Escibano, R. Fernandez Martinez and B.J. Mac Donald

**Author Index** . . . . . 965



<http://www.springer.com/978-3-319-09410-6>

New Trends in Mechanism and Machine Science  
From Fundamentals to Industrial Applications

Flores, P.; Viadero, F. (Eds.)

2015, XVII, 968 p. 529 illus., Hardcover

ISBN: 978-3-319-09410-6