Chapter 2
Optical Waveguide Modes

The optical waveguide is the fundamental element that interconnects the various devices of an optical integrated circuit, just as a metallic strip does in an electrical integrated circuit. However, unlike electrical current that flows through a metal strip according to Ohm’s law, optical waves travel in the waveguide in distinct optical modes. A mode, in this sense, is a spatial distribution of optical energy in one or more dimensions that remains constant in time. In this chapter, the concept of optical modes in a waveguiding structure is discussed qualitatively, and key results of waveguide theory are presented with minimal proof to give the reader a general understanding of the nature of light propagation in an optical waveguide. Then, in Chap. 3, a mathematically sound development of waveguide theory is given.

2.1 Modes in a Planar Waveguide Structure

As shown in Fig. 2.1, a planar waveguide is characterized by parallel planar boundaries with respect to one (x) direction, but is infinite in extent in the lateral directions (z and y). Of course, because it is infinite in two dimensions, it cannot be a practical waveguide for optical integrated circuits, but it forms the basis for the analysis of practical waveguides of rectangular cross section. It has therefore been treated by a number of authors, including McWhorter [1], McKenna [2], Tien [3], Marcuse [4], Taylor and Yariv [5] and Kogelnik [6]. In Section 2.1.2 we follow the approach of Taylor and Yariv [5] to examine the possible modes in a planar waveguide, without fully solving the wave equation.

2.1.1 Theoretical Description of the Modes of a Three-Layer Planar Waveguide

To begin the discussion of optical modes, consider the simple three-layer planar waveguiding structure of Fig. 2.1. The layers are all assumed to be infinite in extent in the y and z directions, and layers 1 and 3 are also assumed to be semi-infinite in the x direction. Light waves are assumed to be propagating in the z direction. It has
been stated previously that a mode is a spatial distribution of optical energy in one or more dimensions. An equivalent mathematical definition of a mode is that it is an electromagnetic field which is a solution of Maxwell’s wave equation

$$\nabla^2 \mathbf{E}(r, t) = \left[ \frac{n^2(r)}{c^2} \right] \frac{\partial^2 \mathbf{E}(r, t)}{\partial t^2}, \quad (2.1)$$

where $\mathbf{E}$ is the electric field vector, $r$ is the radius vector, $n(r)$ is the index of refraction, and $c$ is the speed of light in a vacuum. For monochromatic waves, the solutions of (2.1) have the form

$$\mathbf{E}(r, t) = \mathbf{E}(r) e^{i\omega t}, \quad (2.2)$$

where $\omega$ is the radian frequency. Substituting (2.2) into (2.1) we obtain

$$\nabla^2 \mathbf{E}(r) + k^2 n^2(r) \mathbf{E}(r) = 0, \quad (2.3)$$

where $\kappa \equiv \omega/c$. If we assume, for convenience, a uniform plane wave propagating in the $z$ direction, i.e., $\mathbf{E}(r) = \mathbf{E}(x, y) \exp(-i\beta z)$, $\beta$ being a propagation constant, then (2.3) becomes

$$\frac{\partial^2 \mathbf{E}(x, y)}{\partial x^2} + \frac{\partial^2 \mathbf{E}(x, y)}{\partial y^2} + [k^2 n^2(r) - \beta^2] \mathbf{E}(x, y) = 0. \quad (2.4)$$

Since the waveguide is assumed infinite in the $y$ direction, by writing (2.4) separately for the three regions in $x$, we get

Region 1 \quad \frac{\partial^2 \mathbf{E}(x, y)}{\partial x^2} + (k^2 n_1^2 - \beta^2) \mathbf{E}(x, y) = 0

Region 2 \quad \frac{\partial^2 \mathbf{E}(x, y)}{\partial x^2} + (k^2 n_2^2 - \beta^2) \mathbf{E}(x, y) = 0

Region 3 \quad \frac{\partial^2 \mathbf{E}(x, y)}{\partial x^2} + (k^2 n_3^2 - \beta^2) \mathbf{E}(x, y) = 0, \quad (2.5)$$

where $\mathbf{E}(x, y)$ is one of the Cartesian components of $\mathbf{E}(x, y)$. The solutions of (2.5) are either sinusoidal or exponential functions of $x$ in each of the regions, depending
on whether \((k^2n_i^2 - \beta^2)\), \(i = 1, 2, 3\), is greater than or less than zero. Of course, \(E(x, y)\) and \(\partial E(x, y)/\partial x\) must be continuous at the interface between layers. Hence the possible modes are limited to those shown in Fig. 2.2.

Consider how the mode shape changes as a function of \(\beta\), for the case of constant frequency \(\omega\) and \(n_2 > n_3 > n_1\). This relative ordering of the indices is quite a common case, corresponding, for example, to a waveguiding layer of index \(n_2\) formed on a substrate with smaller index \(n_3\), surrounded by air of index \(n_1\). As we will see in Chapter 3, it is a necessary condition for waveguiding in Layer 2 that \(n_2\) be greater than both \(n_1\) and \(n_3\). When \(\beta > kn_2\), the function \(E(x)\) must be exponential in all three regions and only the mode shape shown as (a) in Fig. 2.2 could satisfy the boundary conditions of \(E(x)\) and \(\partial E(x)/\partial x\) being continuous at the interfaces. This mode is not physically realizable because the field increases unboundedly in Layers 1 and 3, implying infinite energy. Modes (b) and (c) are well confined guided modes, generally referred to as the zeroth order and first order transverse electric modes, \(TE_0\) and \(TE_1\) [7]. For values of \(\beta\) between \(kn_2\) and \(kn_3\) such modes can be supported. If \(\beta\) is greater than \(kn_1\) but less than \(kn_3\), a mode like that in (d) will result. This type of mode, which is confined at the air interface but sinusoidally varying at the substrate, is often called a substrate radiation mode. It can be supported by the waveguide structure, but because it is continually losing energy from the waveguiding Region 2 to the substrate Region 3 as it propagates, it tends to be damped out over short distance. Hence it is not very useful in signal transmission, but, in fact, it may be very useful in coupler applications such as the tapered coupler. This type of coupler will be discussed in Chapter 6. If \(\beta\) is less than \(kn_1\) the solution for \(E(x)\) is oscillatory in all three regions of the waveguide structure. These modes are not guided modes because the energy is free to spread out of the waveguiding Region 2. They are generally referred to as the air radiation modes of the waveguide structure. Of course, radiation is also occurring at the substrate interface.
2.1.2 Cutoff Conditions

We shall see in Chapter 3, when (2.1) is formally solved, subject to appropriate boundary conditions at the interface, that $\beta$ can have any value when it is less than $kn_3$, but only discrete values of $\beta$ are allowed in the range between $kn_3$ and $kn_2$. These discrete values of $\beta$ correspond to the various modes $\text{TE}_j$, $j = 0, 1, 2, \ldots$ (or $\text{TM}_k$, $k = 0, 1, 2, \ldots$). The number of modes that can be supported depends on the thickness $t$ of the waveguiding layer and on $\omega$, $n_1$, $n_2$, and $n_3$. For given $t$, $n_1$, $n_2$, and $n_3$ there is a cutoff frequency $\omega_c$ below which waveguiding cannot occur. This $\omega_c$ corresponds to a long wavelength cutoff $\lambda_c$.

Since wavelength is often a fixed parameter in a given application, the cutoff problem is frequently stated by asking the question, “for a given wavelength, what indices of refraction must be chosen in the three layers to permit waveguiding of a given mode?” For the special case of the so-called asymmetric waveguide, in which $n_1$ is very much less than $n_3$, it can be shown (Chapter 3) that the required indices of refraction are related by

$$\Delta n = n_2 - n_3 = (2m + 1)^2 \frac{\lambda_0^2}{(32n_2t^2)}, \quad (2.6)$$

where the mode number $m = 0, 1, 2, \ldots$, and $\lambda_0$ is the vacuum wavelength. The change in index of refraction required for waveguiding of the lower-order modes is surprisingly small. For example, in a gallium arsenide waveguide with $n_2$ equal to 3.6 [8] and with $t$ on the order of $\lambda_0$, (2.6) predicts that a $\Delta n$ on the order of only $10^{-2}$ is sufficient to support waveguiding of the $\text{TE}_0$ mode.

Because only a small change in index is needed, a great many different methods of waveguide fabrication have proven effective in a variety of substrate materials. The more important of these have been listed in Table 2.1 so that the reader will be familiar with the names of the techniques when they are mentioned in the following discussion of experimental observations of waveguide performance. A thorough explanation of the methods of waveguide fabrication is given in Chapters 4 and 5.

<table>
<thead>
<tr>
<th>Table 2.1 Methods of fabricating waveguides for optical integrated circuits</th>
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<tbody>
<tr>
<td>1) Deposited this films (glass, nitrides, oxides, organic polymers)</td>
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<tr>
<td>2) Photoresist films</td>
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<tr>
<td>3) Ion bombarded glass</td>
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<tr>
<td>4) Diffused dopant atoms</td>
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<tr>
<td>5) Heteroepitaxial layer growth</td>
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<td>6) Electro-optic effect</td>
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<td>7) Metal film stripline</td>
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<td>8) Ion migration</td>
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<td>9) Reduced carrier concentration in a semiconductor</td>
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<tr>
<td>a) epitaxial layer growth</td>
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<td>b) diffusion counterdoping</td>
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<td>c) ion implantation counterdoping or compensation</td>
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2.1.3 **Experimental Observation of Waveguide Modes**

Since the waveguides in optical integrated circuits are typically only a few micrometers thick, observation of the optical mode profile across a given dimension cannot be accomplished without a relatively elaborate experimental set-up, featuring at least 1000× magnification. One such system [9], which works particularly well for semiconductor waveguides, is shown in Fig. 2.3. The sample, with its waveguide at the top surface, is fixed atop an x-y-z micropositioner. Microscope objective lenses, used for input beam coupling and output image magnification, are also mounted on micropositioners to facilitate the critical alignment that is required. The light source is a gas laser, emitting a wavelength to which the waveguide is transparent. For example, a helium-neon laser operating at 1.15 μm is good for GaAs, GaAlAs and GaP waveguides, while one emitting at 6328 Å can be used for GaP but not for GaAlAs or GaAs. For visual observation of the waveguide mode, the output face of the waveguide can be imaged onto either a white screen or an image converter (IC) screen depending on whether visible wavelength or infrared (ir) light is used. The lowest order mode \((m = 0)\) appears as a single band of light, while higher order modes have a correspondingly increased number of bands, as shown in Fig. 2.4.

![Diagram of an experimental setup that can be used to measure optical mode shapes](image-url)
The light image appears as a band rather than a spot because it is confined by the waveguide only in the x direction. Since the waveguide is much wider than it is thick the laser beam is essentially free to diverge in the y direction.

To obtain a quantitative display of the mode profile, i.e. optical power density vs. distance across the face of the waveguide, a rotating mirror is used to scan the image of the waveguide face across a photodetector that is masked to a narrow slit input. The electrical signal from the detector is then fed to the vertical scale of an oscilloscope on which the horizontal sweep has been synchronized with the mirror scan rate. The result is in the form of graphic displays of the mode shape, like those shown in Fig. 2.5. Note that the modes have the theoretically predicted sinusoidal-exponential shape, by remembering that what is observed is optical power density, or intensity, which is proportional to $E^2$. Details of the mode shape, like the rate of exponential decay (or extinction) of the evanescent “tail” extending across the waveguide-substrate and waveguide-air interfaces, depend strongly on the values of $\Delta$ at the interface. As can be seen in Fig. 2.5, the extinction is much sharper at
2.1 Modes in a Planar Waveguide Structure

Fig. 2.5 Optical mode shapes are measured using the apparatus of Fig. 2.3. The waveguide in this case was formed by proton implantation into a gallium arsenide substrate to produce a 5 μm thick carrier-compensated layer [12].

The waveguide-air interface where $\Delta n \approx 2.5$ than at the waveguide-substrate plane where $\Delta n \approx 0.01–0.1$.

A system like that shown in Fig. 2.3 is particularly useful for analysis of mode shapes in semiconductor waveguides, which generally support only one or two modes because of the relatively small $\Delta n$ at the waveguide-substrate interface. Generally, the position of the focused input laser beam can be moved toward the center of the waveguide to selectively pump the zeroth order mode, or toward either the air or substrate interface to select the first order mode. It becomes very difficult to visually resolve the light bands in the case of higher-order, multimode waveguides because of spatial overlapping, even though the modes may be electromagnetically distinct and non-coupled one to another. Waveguides produced by depositing thin films of oxides, nitrides or glasses onto glass or semiconductor substrates usually are multi-mode, supporting 3 or more modes, because of the larger waveguide-substrate $\Delta n$ [11–14]. For waveguides of this type, a different experimental technique, employing prism coupling, is most often used to analyze the modes.

The prism coupler will be discussed in detail in Chapter 7. At this point it suffices to say that the prism coupler has the property that it selectively couples light into (or out of) a particular mode, depending on the angle of incidence (or emergence). The mode-selective property of the prism coupler, which is illustrated in Fig. 2.6, results from the fact that light in each mode within a waveguide propagates at a different velocity, and continuous phase-matching is required for coupling. The particular angle of incidence required to couple light into a given mode or the angle of emergence of light coupled out of a given mode can both be accurately calculated from theory, as will be seen in Chapter 7. The prism coupler can thus be used to analyze the modes of a waveguide. This can be done in two ways.

In one approach, the angle of incidence of a collimated, monochromatic laser beam on an input coupler prism is varied and the angles for which a propagating optical mode is introduced into the waveguide are noted. The propagation of optical energy in the waveguide can be observed by merely placing a photodetector at the...
output end of the waveguide. One can then determine which modes the waveguide is capable of supporting by calculating from the angle of incidence data.

An alternative method uses the prism as an output coupler. In this case, monochromatic light is introduced into the waveguide in a manner so as to excite all of the waveguide modes. For example, a diverging laser beam, either from a semiconductor laser, or from a gas laser beam passed through a lens to produce divergence, is focused onto the input face of the waveguide. Since the light is not collimated, but rather enters the waveguide at a variety of angles, some energy is
introduced into all of the waveguide modes for which the waveguide is above cutoff at the particular wavelength used. If a prism is then used as an output coupler, light from each mode emerges from the prism at a different angle. Again, the particular modes involved can be determined by calculation from the emergence angle data. Since the thickness of the waveguide is much less than its width, the emerging light from each mode appears as a band, producing a series of so-called “m” lines as shown in Fig. 2.7, corresponding to the particular mode number.

When the prism coupler is used to analyze the modes of a waveguide, the actual mode shape, or profile, cannot be determined in the same way as that of the scanning mirror approach of Fig. 2.3. However, the prism coupler method lets one determine how many modes can be supported by a multimode waveguide, and, as will be seen in Chap. 6, the phase velocity (hence the effective index of refraction) for each mode can be calculated from incidence and emergence angle data.

2.2 The Ray-Optic Approach to Optical Mode Theory

In Section 2.1, we considered the propagation of light in a waveguide as an electromagnetic field which mathematically represented a solution of Maxwell’s wave equation, subject to certain boundary conditions at the interfaces between planes of different indices of refraction. Plane waves propagating along the z direction, supported one or more optical modes. The light propagating in each mode traveled in the z direction with a different phase velocity, which is characteristic of that mode. This description of wave propagation is generally called the physical-optic approach. An alternative method, the so-called ray-optic approach [6, 15, 16, 17], is also possible but provides a less complete description. In this latter formulation, the light propagating in the z direction is considered to be composed of plane waves moving in zig-zag paths in the x-z plane undergoing total internal reflection at the interfaces bounding the waveguide. The plane waves comprising each mode travel with the same phase velocity. However, the angle of reflection in the zigzag path is different for each mode, making the z component of the phase velocity different. The plane waves are generally represented by rays drawn normal to the planes of constant phase as shown in Fig. 2.8, which explains the name ray-optic.

![Fig. 2.8 Optical ray pattern within a multimode planar waveguide](image_url)
2.2.1 Ray Patterns in the Three-Layer Planar Waveguide

The ray patterns shown in Fig. 2.8 correspond to two modes, say the TE\(_{0}\) and TE\(_{1}\), propagating in a three layer waveguide with \(n_2 > n_3 > n_1\). The electric (\(E\)) and magnetic (\(H\)) fields of these plane waves traveling along zig-zag paths would add vectorially to give the \(E\) and \(H\) distributions of the waves comprising the same two modes, propagating in the \(z\) direction, that were described by the physical-optic model of Section 2.1. Both the ray-optic and physical-optic formulations can be used to represent either TE waves, with components \(E_y\), \(H_z\), and \(H_x\), or TM waves, with components \(H_y\), \(E_z\) and \(E_x\).

The correlation between the physical-optic and ray-optic approaches can be seen by referring back to (2.5). The solution to this equation in the waveguiding Region 2 has the form [2.5]:

\[
E_y(x, z) \propto \sin(hx + \gamma),
\]

(2.7)

where a TE mode has been assumed, and where \(h\) and \(\gamma\) are dependent on the particular waveguide structure. Substituting (2.7) into (2.5) for Region 2, one obtains the condition

\[
\beta^2 + h^2 = k^2 n_2^2. \tag{2.8}
\]

Remembering that \(k \equiv \omega / c\), it can be seen that \(\beta\), \(h\) and \(kn_2\) are all propagation constants, having units of \((\text{length})^{-1}\). A mode with a \(z\) direction propagation constant \(\beta_m\) and an \(x\) direction propagation constant \(h\) can thus be represented by a plane wave travelling at an angle \(\theta_m = \tan^{-1}(h/\beta_m)\) with respect to the \(z\) direction, having a propagation constant \(kn_2\), as diagrammed in Fig. 2.9. Since the frequency is constant, \(kn_2 \equiv (\omega / c)n_2\) is also constant, while \(\theta_m\), \(\beta_m\) and \(h\) are all parameters associated with the \(m\)th mode, with different values for different modes.

To explain the waveguiding of light in a planar three-layer guide like that of Fig. 2.8 by the ray-optic method, one needs only Snell’s law of refraction, coupled with the phenomenon of total internal reflection. For a thorough discussion of these basic concepts of optics see, for example, Condon [18], or Billings [19], or Benett [20]. Consider a ray of light propagating within a three-layer waveguide structure as shown in Fig. 2.10. The light rays of Fig. 2.10a,b and c correspond to a radiation mode, a substrate mode, and a guided mode, respectively. The angles of incidence

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**Fig. 2.9** Geometric (vectorial) relationship between the propagation constants of an optical waveguide

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2.2 The Ray-Optic Approach to Optical Mode Theory

Fig. 2.10 a, b, c. Optical ray patterns for a air radiation modes; b substrate radiation modes; c guided mode. In each case a portion of the incident light is reflected back into layer 3; however, that ray has been omitted from the diagrams

and refraction, $\varphi_i$, with $i = 1, 2, 3$, are measured with respect to the normals to the interface planes, as is common practice in optics. From Snell’s law

$$\sin \varphi_1 / \sin \varphi_2 = n_2 / n_1$$

(2.9)

and

$$\sin \varphi_2 / \sin \varphi_3 = n_3 / n_2.$$ 

(2.10)

Beginning with very small angles of incidence, $\varphi_3$, near zero, and gradually increasing $\varphi_3$, we find the following behavior. When $\varphi_3$ is small, the light ray passes freely through both interfaces, suffering only refraction, as in Fig. 2.10a. This case corresponds to the radiation modes discussed in Section 2.1. As $\varphi_3$ is increased beyond the point at which $\varphi_2$ exceeds the critical angle for total internal reflection at the $n_2 - n_1$ interface, that light wave becomes partially confined as shown in Fig. 2.10b, corresponding to a substrate radiation mode. The condition for total internal reflection at the $n_2 - n_1$ interface is given by [19]

$$\varphi_2 \geq \sin^{-1}(n_1 / n_2),$$

(2.11)

or, combining (2.11) and (2.10),

$$\varphi_3 \geq \sin^{-1}(n_1 / n_3).$$

(2.12)

As $\varphi_3$ is further increased beyond the point at which $\varphi_2$ also exceeds the critical angle for total internal reflection at the $n_2 - n_3$ interface, the lightwave becomes totally confined, as shown in Fig. 2.10c, corresponding to a guided mode. In this case, the critical angle is given by

$$\varphi_2 \geq \sin^{-1}(n_3 / n_2),$$

(2.13)

or, combining (2.2.7) and (2.2.4),

$$\varphi_3 \geq \sin^{-1}(1) = 90^\circ.$$ 

(2.14)
The conditions given by (2.11) and (2.13) for determining what type of modes can be supported by a particular waveguide as a function of $\varphi_2$ are exactly equivalent to the conditions given by (2.11) as a function of $\beta$. For example, (2.5) indicates that only radiation modes result for $\beta$ less than $k_n$. Referring to Fig. 2.9, note that,

$$\varphi_2 = \beta / k_n.$$  \hspace{1cm} (2.15)

Thus, if $\beta \leq k_n$,

$$\varphi_2 \leq k_n / k_n = n_1 / n_2,$$  \hspace{1cm} (2.16)

which is the same condition given by (2.11). Similarly, if $\beta$ is greater than $k_n$ but less than $k_n$, (2.5) indicates that substrate radiation modes will be supported. Only when $\beta \geq k_n$, can confined waveguide modes occur. From Fig. 2.9, if $\beta \geq k_n$,

$$\sin \varphi_2 = \beta / k_n \geq k_n / k_n \geq n_3 / n_2.$$  \hspace{1cm} (2.17)

Equation (2.17), obtained from physical-optic theory, is merely a repeat of (2.13) that resulted from the ray-optic approach. Finally, if $ft$ is greater than $k_n$,

$$\sin \varphi_2 = \beta / k_n \geq 1.$$  \hspace{1cm} (2.18)

Equation (2.18) is, of course, a physically unrealizable equality, corresponding to the physically unrealizable “a” type of modes of Fig. 2.2. Thus an equivalence has been demonstrated between the ray-optic and physical-optic approaches in regard to the determination of mode type.

### 2.2.2 The Discrete Nature of the Propagation Constant $\beta$

The correspondence between the ray-optic and physical optic formalisms extends beyond merely determining what type modes can be supported. It has been mentioned previously, and will be demonstrated mathematically in Chapter 3, that the solution of Maxwell’s equation subject to the appropriate boundary conditions requires that only certain discrete values of $\beta$ are allowed. Thus, there are only a limited number of guided modes that can exist when $\beta$ is in the range

$$k_n \leq \beta \leq k_n.$$  \hspace{1cm} (2.19)

This limitation on $\beta$ can be visualized quite conveniently using the ray-optic approach. The plane wavefronts that are normal to the zig-zag rays of Fig. 2.8 are assumed to be infinite, or at least larger than the cross section of the waveguide that is intercepted; otherwise they would not fit the definition of a plane wave, which requires a constant phase over the plane. Thus, there is much overlapping of the waves as they travel in the zig-zag path. To avoid decay of optical energy due to
destructive interference as the waves travel through the guide, the total phase change for a point on a wavefront that travels from the $n_2 - n_3$ interface to the $n_2 - n_1$ interface and back again must be a multiple of $2\pi$. This leads to the condition,

$$2kn_2t \sin \theta_m - 2\varphi_{23} - 2\varphi_{21} = 2m\pi,$$

where $t$ is the thickness of the waveguiding Region 2, $\theta_m$ is the angle of reflection with respect to the $z$ direction, as shown in Fig. 2.8, $m$ is the mode number, and $\varphi_{23}$ and $\varphi_{21}$, are the phase changes suffered upon total internal reflection at the interfaces. The phases $-2\varphi_{23}$ and $-2\varphi_{21}$, represent the Goos-Hänchen shifts [21, 22]. These phase shifts can be interpreted as penetration of the zig-zag ray (for a certain depth $\delta$) into the confining layers 1 and 3 before it is reflected [6, pp. 25–29].

The values of $\varphi_{23}$ and $\varphi_{21}$ can be calculated from [22]:

$$\tan \varphi_{23} = (n_2^2 \sin^2 \varphi_2 - n_3^2)^{1/2} / (n_2 \cos \varphi_2)$$

$$\tan \varphi_{21} = (n_2^2 \sin^2 \varphi_2 - n_1^2)^{1/2} / (n_2 \cos \varphi_2)$$

(2.21)

for TE waves, and

$$\tan \varphi_{23} = n_2^2(n_2^2 \sin^2 \varphi_2 - n_3^2)^{1/2} / (n_3^2n_2 \cos \varphi_2)$$

$$\tan \varphi_{21} = n_2^2(n_2^2 \sin^2 \varphi_2 - n_1^2)^{1/2} / (n_1^2n_2 \cos \varphi_2)$$

(2.22)

for TM waves.

It can be seen that substitution of either (2.21) or (2.22) into (2.20) results in a transcendental equation in only one variable, $\theta_m$, or $\varphi_m$, where

$$\varphi_m = \frac{\pi}{2} - \theta_m.$$  

(2.23)

For a given $m$, the parameters $n_1$, $n_2$, $n_3$ and $t$, $\varphi_m$ (or $\theta_m$) can be calculated. Thus a discrete set of reflection angles $\varphi_m$ are obtained corresponding to the various modes. However, valid solutions do not exist for all values of $m$. There is a cutoff condition on allowed values of $m$ for each set of $n_1$, $n_2$, $n_3$ and $t$, corresponding to the point at which $\varphi_m$ becomes less than the critical angle for total internal reflection at either the $n_2 - n_3$ or the $n_2 - n_1$ interface, as discussed in Section 2.2.1.

For each allowed mode, there is a corresponding propagation constant $\beta_m$ given by

$$\beta_m = kn_2 \sin \varphi_m = kn_2 \cos \theta_m.$$  

(2.24)

The velocity of the light parallel to the waveguide is then given by

$$v = c(k/\beta),$$  

(2.25)

and one can define an effective index of refraction for the guide as
Chapter 2 has described the optical modes that can exist in a three-layer planar waveguide. We have seen that the modes can be described either by a physical-optic method, based on a solution of Maxwell’s wave equation, or by a ray-optic method, relying on geometrical ray tracing principles of classical optics. In Chapter 3, the mathematical model underlying the mode theory will be developed in greater detail.

**Problems**

2.1 We wish to fabricate a planar waveguide in GaAs for light of wavelength $\lambda_0 = 1.1 \, \mu\text{m}$ that will operate in the single (fundamental) mode. If we assume a planar waveguide like that of Fig. 2.1 with the condition $n_2 - n_1 >> n_2 - n_3$, what range of values can $n_2 - n_3$ have if $n_2 = 3.4$ and the thickness of the waveguiding layer $t = 3 \, \mu\text{m}$?

2.2 Repeat Problem 2.1 for the case $\lambda_0 = 1.06 \, \mu\text{m}$, all other parameters remaining unchanged.

2.3 Repeat Problems 2.1 and 2.2 for a waveguide of thickness $t = 6 \, \mu\text{m}$.

2.4 In a planar waveguide like that of Fig. 2.8 with $n_2 = 2.0$, $n_3 = 1.6$, and $n_1 = 1$, what is the angle of propagation of the lowest order mode ($\theta_0$) when cutoff occurs? Is this a maximum or a minimum angle for $\theta_0$?

2.5 Sketch the three lowest order modes in a planar waveguide like that of Fig. 2.8 with $n_1 = n_3 < n_2$.

2.6 A mode is propagating in a planar waveguide as shown with $\beta_m = 0.8 \, k n_2$. How many reflections at the $n_1 - n_2$ interface does the ray experience in traveling a distance of 1 cm in the $z$ direction?

2.7 Show that the Goos–Hänchen phase shift goes to zero as the cutoff angle is approached for a waveguided optical mode.

2.8 Calculate the Goos–Hänchen shifts for a TE mode guided with $\beta = 1.85 \, k$ in a guide like that of Fig. 2.8, with $n_1 = 1.0$, $n_2 = 2.0$, $n_3 = 1.7$.

2.9 Show by drawing the vectorial relationship between the propagation constants (as in Fig. 2.9) How $\beta$, $kn_2$ and $h$ change in relative magnitude and angle as one goes from the lowest-order mode in a waveguide progressively to higher-order modes.
2.2 The Ray-Optic Approach to Optical Mode Theory

2.10 A planar asymmetric waveguide is fabricated by depositing a 2 μm thick layer of Ta$_2$O$_5$ ($n = 2.09$) on to a quartz substrate ($n = 1.05$).

(a) How many modes can this waveguide support for light of 6328 Å (vacuum wavelength)?

(b) If a 20 (μm) layer of quartz ($n = 1.05$) is deposited on top of the Ta$_2$O$_5$ waveguide, how many modes can it support for light of 6328 Å (vacuum wavelength)?

2.11 (a) Find the minimum required thickness for a planar slab waveguide with index of refraction = 3.5 on a substrate with index = 3.38 if it is to support the propagation of the lowest order TE mode of light with a vacuum wavelength 880 nm. The medium surrounding the waveguide and substrate is air.

(b) If the thickness of the waveguide were increased above its minimum value by a factor of 2, and all other parameters remained unchanged, how many TE modes could be supported?

References

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