

# Contents

<b>1</b>	<b>Evolutionary computation</b> .....	1
1.1	Natural and artificial evolution .....	1
1.2	The classical paradigms .....	4
1.3	Genetic programming .....	7
<b>2</b>	<b>Why yet another one evolutionary optimizer?</b> .....	9
2.1	Background .....	9
2.2	Where to draw the lines .....	10
2.3	Individuals .....	11
2.4	Problem specification .....	13
2.5	Coding Techniques .....	14
<b>3</b>	<b>The <math>\mu</math>GP architecture</b> .....	17
3.1	Conceptual design .....	18
3.2	The evolutionary core .....	18
3.2.1	Evolutionary Operators .....	19
3.2.2	Population .....	20
3.3	The Evolutionary Cycle .....	21
3.3.1	Genetic operator selection .....	21
3.3.2	Parents selection .....	22
3.3.3	Offspring Generation .....	23
3.3.4	Individual Evaluation and Slaughtering .....	24
3.3.5	Termination and Aging .....	24
<b>4</b>	<b>Advanced features</b> .....	27
4.1	Self adaptation for exploration or exploitation .....	27
4.1.1	Self-adaptation inertia .....	28
4.1.2	Operator strength .....	28
4.1.3	Tournament size .....	29
4.2	Escaping local optimums .....	29
4.2.1	Operator activation probability .....	30

4.2.2	Tuning the elitism . . . . .	30
4.3	Preserving diversity . . . . .	31
4.3.1	Clone detection, scaling and extermination . . . . .	32
4.3.2	Entropy and delta-entropy computation . . . . .	32
4.3.3	Fitness holes . . . . .	33
4.3.4	Population topology and multiple populations . . . . .	34
4.4	Coping with the real problems . . . . .	35
4.4.1	Parallel fitness evaluation . . . . .	36
4.4.2	Multiple fitness . . . . .	37
<b>5</b>	<b>Performing an evolutionary run . . . . .</b>	<b>39</b>
5.1	Robot Pathfinder . . . . .	41
5.2	$\mu$ GP Settings . . . . .	43
5.3	Population Settings . . . . .	45
5.4	Library of Constraints . . . . .	49
5.5	Launching the experiment . . . . .	53
5.6	$\mu$ GP Extractor . . . . .	55
<b>6</b>	<b>Command line syntax . . . . .</b>	<b>57</b>
6.1	Starting a run . . . . .	57
6.2	Controlling messages to the user . . . . .	58
6.3	Getting help and information . . . . .	59
6.4	Controlling logging . . . . .	59
6.5	Controlling recovery . . . . .	60
6.6	Controlling evolution . . . . .	61
6.7	Controlling evaluation . . . . .	62
<b>7</b>	<b>Syntax of the settings file . . . . .</b>	<b>65</b>
7.1	Controlling evolution . . . . .	66
7.2	Controlling logging . . . . .	68
7.3	Controlling recovery . . . . .	69
<b>8</b>	<b>Syntax of the population parameters file . . . . .</b>	<b>71</b>
8.1	Strategy parameters . . . . .	71
8.1.1	Base parameters . . . . .	72
8.1.2	Parameters for self adaptation . . . . .	75
8.1.3	Other parameters . . . . .	78
<b>9</b>	<b>Syntax of the external constraints file . . . . .</b>	<b>81</b>
9.1	Purposes of the constraints . . . . .	81
9.2	Organization of constraints and hierarchy . . . . .	82
9.3	Specifying the structure of the individual . . . . .	87
9.4	Specifying the contents of the individual . . . . .	90

<b>10 Writing a compliant evaluator</b> .....	97
10.1 Information from $\mu$ GP to the fitness evaluator .....	97
10.2 Expected fitness format .....	98
10.2.1 Good Examples .....	99
10.2.2 Bad Examples .....	100
<b>11 Implementation details</b> .....	103
11.1 Design principles .....	103
11.2 Architectural choices .....	104
11.2.1 The Graph library .....	105
11.2.2 The Evolutionary Core library .....	107
11.2.3 Front end .....	114
11.3 Code organization and class model .....	114
<b>12 Examples and applications</b> .....	125
12.1 Classical one-max .....	125
12.1.1 Fitness evaluator .....	126
12.1.2 Constraints .....	128
12.1.3 Population settings .....	130
12.1.4 $\mu$ GP settings .....	132
12.1.5 Running .....	133
12.2 Values of parameters and their influence on the evolution:	
Arithmetic expressions .....	134
12.2.1 De Jong 3 .....	134
12.2.2 De Jong 4 - Modified .....	139
12.2.3 Carrom .....	140
12.3 Complex individuals' structures and evaluation:	
Bit-counting in Assembly .....	146
12.3.1 Assembly individuals representation .....	146
12.3.2 Evaluator .....	149
12.3.3 Running .....	151
<b>Argument and option synopsis</b> .....	153
<b>External constraints synopsis</b> .....	169
<b>References</b> .....	177



<http://www.springer.com/978-0-387-09425-0>

Evolutionary Optimization: the  $\mu$ GP toolkit

Sanchez, E.; Schillaci, M.; Squillero, G.

2011, XIII, 178 p., Hardcover

ISBN: 978-0-387-09425-0